

# Human-Centered AI to foster Explainability and Robustness for Trustworthy AI



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with effect of March, 1, 2022: University of Natural Resources and Life Sciences Vienna, Austria  
and  
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# ORGANIZERS

- **Elizabeth Daly (Workshop Chair)**, IBM Research,
- **Öznur Alkan**, IBM Research, Dublin
- **Stefano Teso**, University of Trento
- **Wolfgang Stammer**, TU Darmstadt

- FWF P-32554 xAI - A reference model of explainable Artificial Intelligence for digital medicine
- EU RIA 826078 FeatureCloud - Trusted digital federated solutions and Cybersecurity in health
- EU RIA 874662 HEAP - Human Exposome: digital toolbox for assessing and addressing environmental impact on health
- FFG 879881 EMPAIA – Digital Ecosystem for Pathology Diagnostics with AI Assistance

- **(0) Motivation ...**
- **(1) Examples ...**
- **(2) Challenges ...**
- **(3) Human-in-the-loop ...**
- **(4) Explainability ...**
- **(5) Causability ...**

# (0) Motivation



- **Trust** := *subjective* belief/assessment incl. security, dependability, integrity, predictability, reliability (always as expectation!)
- **Trustworthy AI** := *ensures* security, safety, privacy, non-discrimination, fairness, accountability (re-traceability, replicability), auditability and environmental well-being, and most of all robustness and explainability
- **Robustness** := to produce reliable results even if the input data is perturbed
- **Explainability** := technically *highlights* decision relevant parts of machine representations and machine models i.e., parts which contributed to model accuracy in training, or to a specific prediction.
  - Explainability does *not* refer to a human model!
- **Causability** := the measurable extent to which an explanation of a statement to a user achieves a specified level of *causal understanding* with effectiveness, efficiency, satisfaction in a specified context of use.
  - Causability does refer to a *human model* !

Andreas Holzinger, Matthias Dehmer, Frank Emmert-Streib, Rita Cucchiara, Isabelle Augenstein, Javier Del Ser, Wojciech Samek, Igor Jurisica & Natalia Díaz-Rodríguez (2021). Information fusion as an integrative cross-cutting enabler to achieve robust, explainable, and trustworthy medical artificial intelligence. Information Fusion, 79, (3), 263-278, doi:10.1016/j.inffus.2021.10.007.

# (1) Examples ...

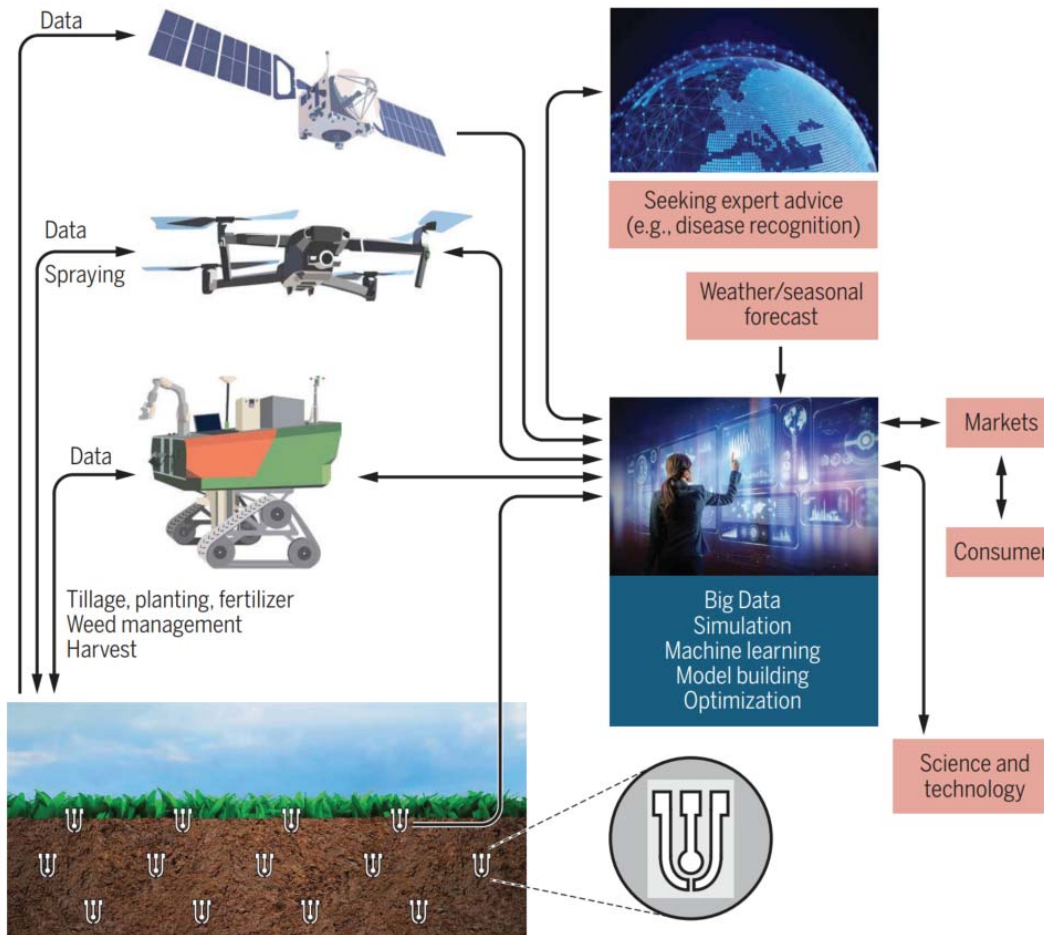




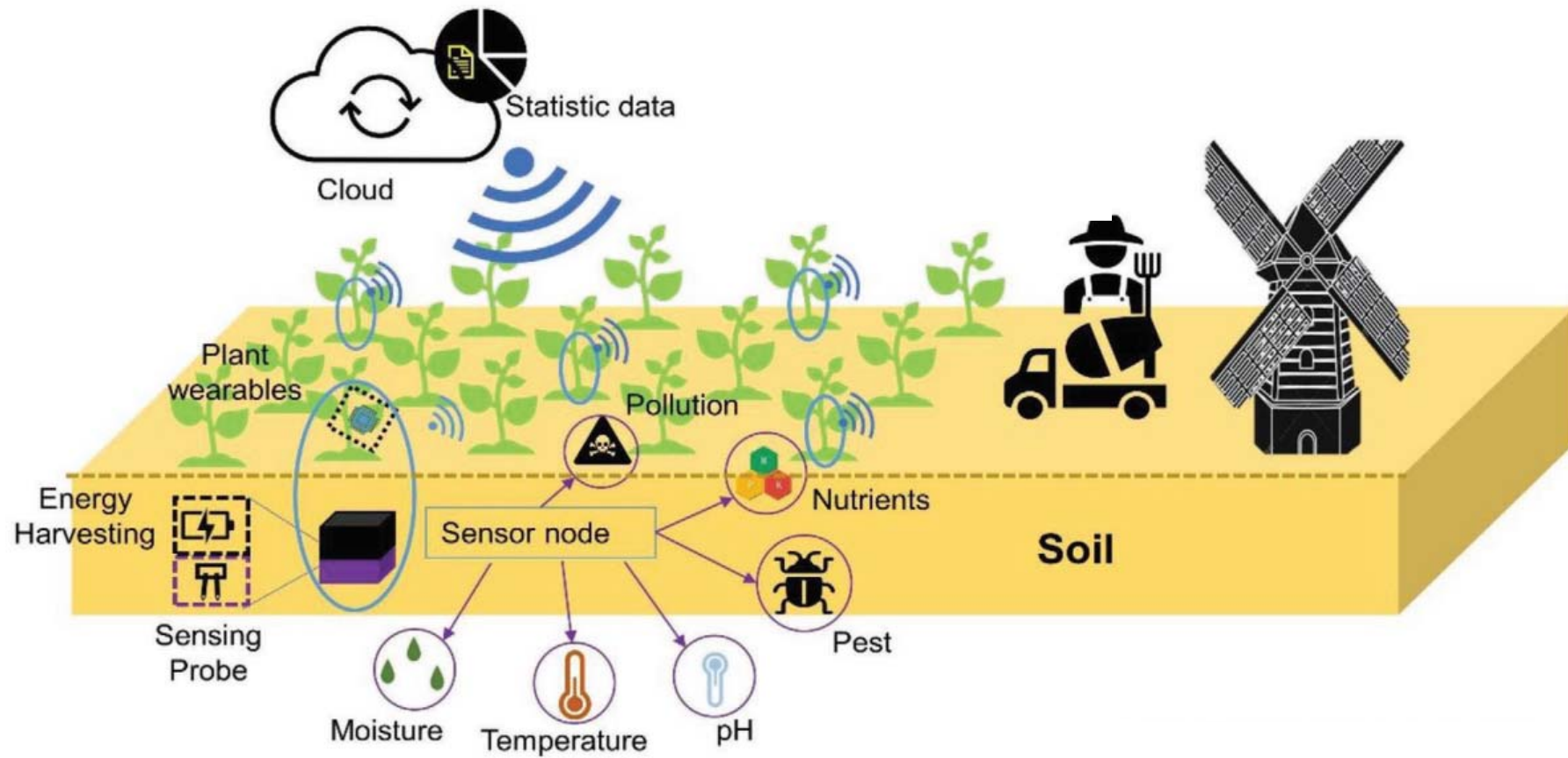
Source: BMFL



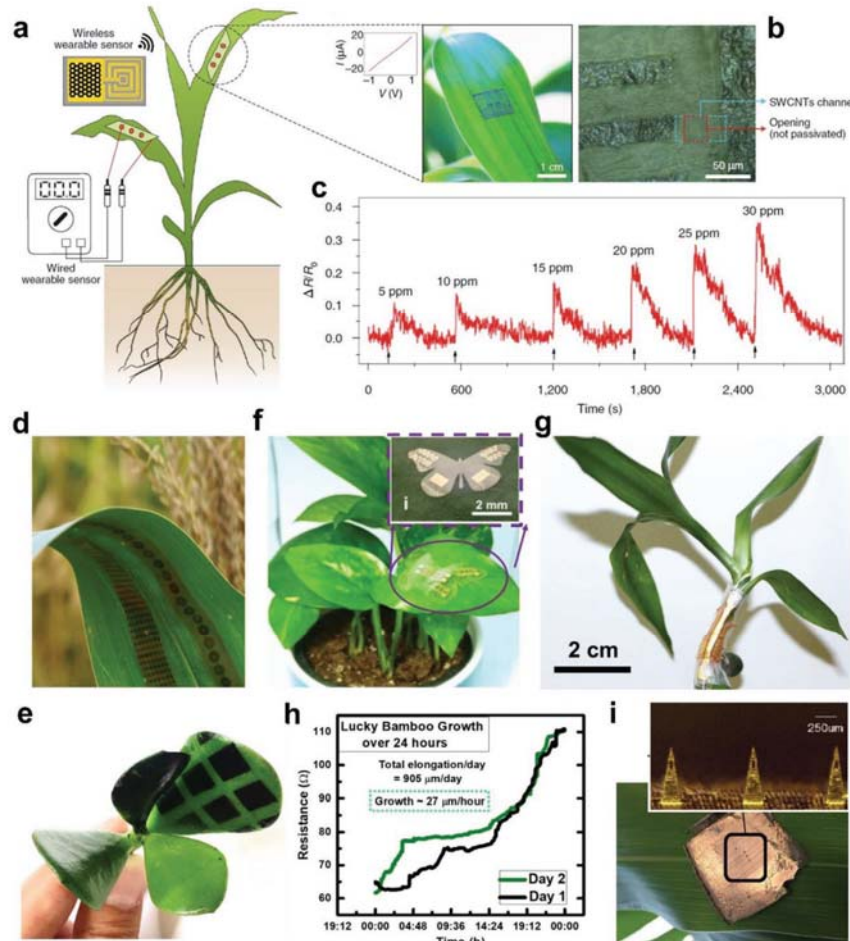
Source: hardwoodsnb.ca



Senthold Asseng & Frank Asche (2019). Future farms without farmers. *Science Robotics*, 4, (27), 1-2, doi:10.1126/scirobotics.aaw1875.

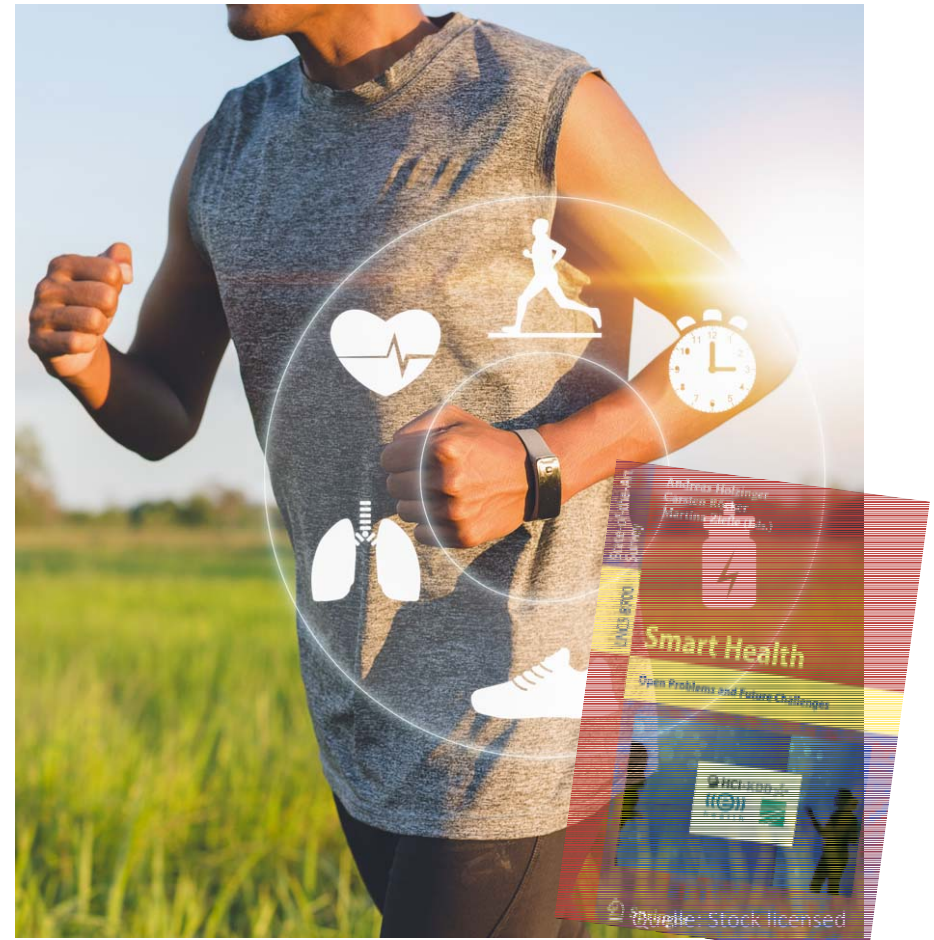


Heyu Yin, Yunteng Cao, Benedetto Marelli, Xiangqun Zeng, Andrew J. Mason & Changyong Cao (2021). Soil Sensors and Plant Wearables for Smart and Precision Agriculture. *Advanced Materials*, 33, (20), 2007764, doi:10.1002/adma.202007764.



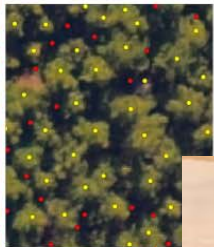
andreas.holzinger AT human-centered.ai Quelle: Yin et. al (2021) doi: 10.1002/adma.202007764

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<https://human-centered.ai/Innovations-in-Smart-Health-Machine-Learning>, February, 28, 2022

## Training

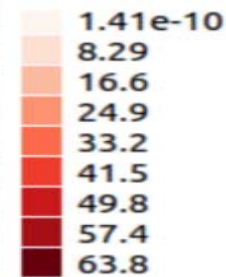
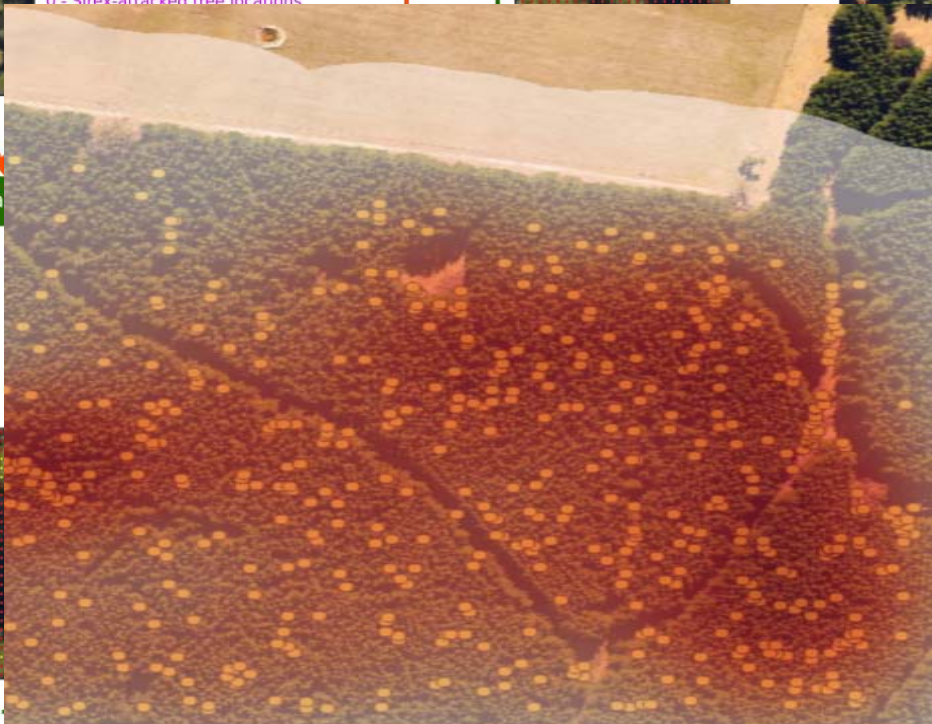
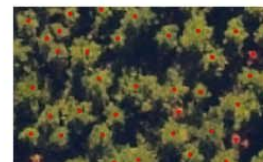
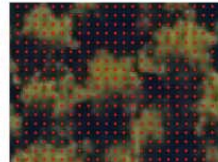


**annotations:**  
 tree detection  
 1 - tree-top locations  
 0 - non-tree-top locations

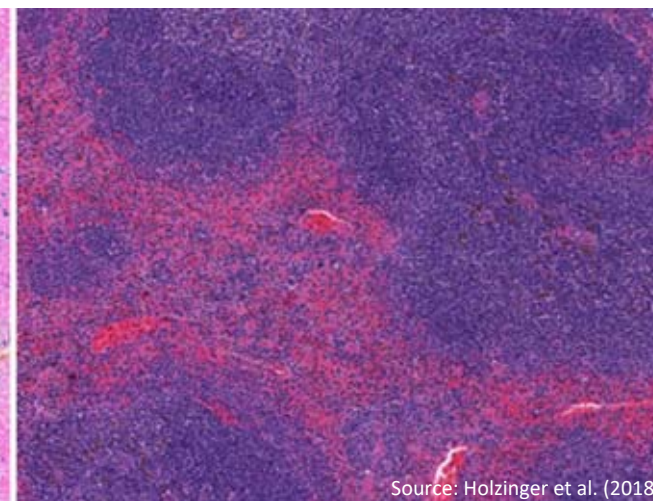
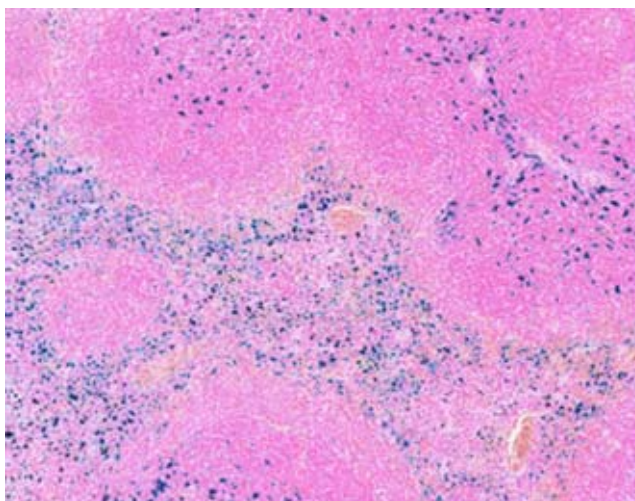
**health classification:**  
 1 - healthy tree locations  
 0 - Sirex-attacked tree locations

fea

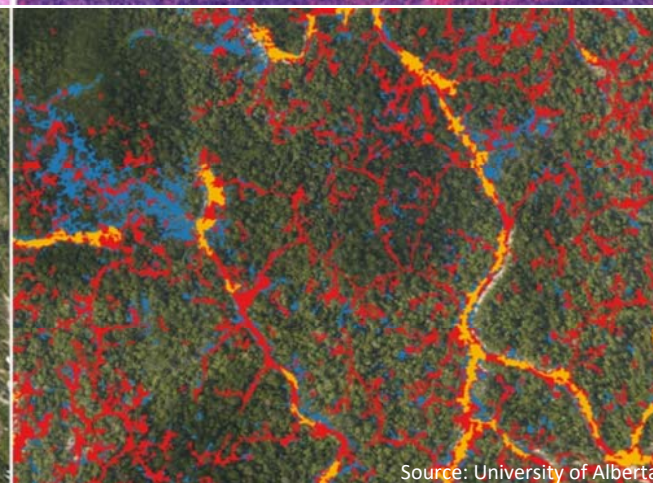
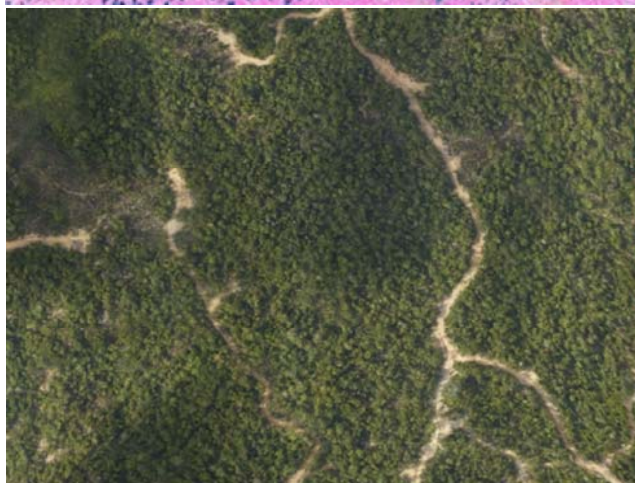
## Inference for detection or classification



Fleur Jeanquartier, Claire Jean-Quartier, David Cemernek & Andreas Holzinger (2016). In silico modeling for tumor growth visualization. BMC Systems Biology, 10, (1), 1-15, doi:10.1186/s12918-016-0318-8.



Source: Holzinger et al. (2018)



Source: University of Alberta

Robert S. Allison, Joshua M. Johnston, Gregory Craig & Sion Jennings (2016). Airborne optical and thermal remote sensing for wildfire detection and monitoring. Sensors, 16, (8), 1310, doi:10.3390/s16081310.

$\mathcal{D}$  ... data  $\mathcal{D} = x_{1:n} = \{x_1, x_2, \dots, x_n\}$

$\theta$  ... features prior:  $p(\theta)$  likelihood:  $p(\mathcal{D}|\theta)$

Posterior  $\approx p(\theta)$  of  $\theta$  after seen ("learned")  $\mathcal{D}$  :  $p(\theta|\mathcal{D})$

$$\text{posterior} = \frac{\text{likelihood} * \text{prior}}{\text{evidence}}$$

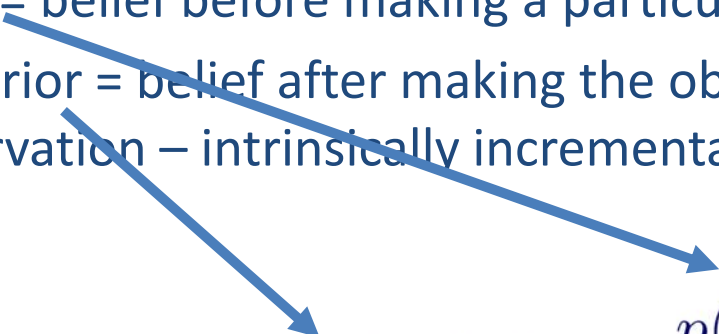
$$p(\theta|\mathcal{D}) = \frac{p(\mathcal{D}|\theta) * p(\theta)}{p(\mathcal{D})}$$

**The inverse probability allows us to learn from data, infer unknowns, and make predictions ...**



*"Il est remarquable qu'une science qui a commencé avec l'ère la prise en compte des jeux de hasard ... aurait dû devenir l'objet le plus important de la connaissance humaine." Laplace (1812)*

- Take patient information, e.g., observations, symptoms, test results, -omics data, etc. etc.
- Reach conclusions, and **predict** into the future, e.g. how likely will the patient be ...
- Prior = belief before making a particular observation
- Posterior = belief after making the observation and is the prior for the next observation – intrinsically incremental


$$p(x_i|y_j) = \frac{p(y_j|x_i)p(x_i)}{\sum p(x_i, y_j)p(x_i)}$$



Source: Stock licensed

## (2) Challenges ...



See also: Ian J. Goodfellow, Jonathon Shlens & Christian Szegedy 2014. Explaining and harnessing adversarial examples. arXiv:1412.6572.



classified as  
**Stop Sign**

$+ .007 \times$



$\text{sign}(\nabla_x J(\theta, x, y))$   
“nematode”  
8.2% confidence

=



classified as  
**Max Speed 100**

Ian J. Goodfellow, Jonathon Shlens & Christian Szegedy (2014). Explaining and harnessing adversarial examples. arXiv:1412.6572  
Traffic Sign Examples Image Credit to Jiefeng Chen & Xi Wu (2019). <https://www.altacognita.com/robust-attribution>

## Adversarial Examples that Fool both Computer Vision and Time-Limited Humans

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**Shreya Shankar**  
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**Brian Cheung**  
UC Berkeley

**Nicolas Papernot**  
Pennsylvania State University

**Alex Kurakin**  
Google Brain

**Ian Goodfellow**  
Google Brain

**Jascha Sohl-Dickstein**  
Google Brain  
jaschasd@google.com

### Abstract

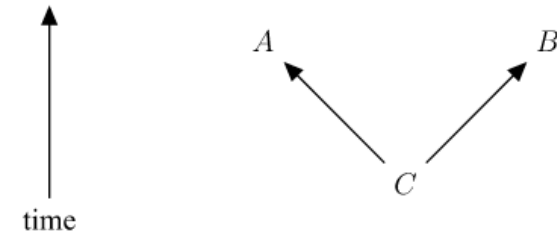
Machine learning models are vulnerable to **adversarial examples**: small changes to images can cause computer vision models to make mistakes such as identifying a school bus as an ostrich. However, it is still an open question whether humans are prone to similar mistakes. Here, we address this question by leveraging recent techniques that transfer adversarial examples from computer vision models with known parameters and architecture to other models with unknown parameters and architecture, and by matching the initial processing of the human visual system. We find that adversarial examples that strongly transfer across computer vision models influence the classifications made by time-limited human observers.

Gamaleldin F Elsayed, Shreya Shankar, Brian Cheung, Nicolas Papernot, Alex Kurakin, Ian Goodfellow & Jascha Sohl-Dickstein 2018. Adversarial Examples that Fool both Human and Computer Vision. arXiv:1802.08195.

- 1) learning from few **data**
- 2) extracting **knowledge**
- 3) **generalize**
- 4) fight the curse of **dimensionality**
- 5) disentangle the **independent** explanatory factors of data, i.e.
- 6) **causal understanding** of the data in the **context** of an application domain

# **(3) Correlation $\neq$ Causality and the Human-in-the-loop**

- Hans Reichenbach (1891-1953):  
**Common Cause Principle**  
 Links causality with probability:
  - If A and B are statistically dependent,  
 there is a C influencing both
  - Whereas:
  - A, B, C ... events
  - p ... probability density



$$p(A \cap B) > p(A)p(B)$$

$$p(A \cap B|C) = p(A|C)p(B|C)$$

$$p(A \cap B|\bar{C}) = p(A|\bar{C})p(B|\bar{C})$$

$$p(A|C) > p(A|\bar{C})$$

$$p(B|C) > p(B|\bar{C})$$

$$p(X|Y) \doteq \frac{p(X \cap Y)}{p(Y)}$$

Hans Reichenbach 1956. The direction of time  
 (Edited by Maria Reichenbach), Mineola, New York, Dover.

Hitchcock, Christopher and Miklós Rédei, "Reichenbach's Common Cause Principle",  
 The Stanford Encyclopedia of Philosophy (Spring 2020 Edition), Edward N. Zalta (ed.),  
 Online available: <https://plato.stanford.edu/archives/spr2020/entries/physics-Rpcc>

## Storks Deliver Babies ( $p = 0.008$ )

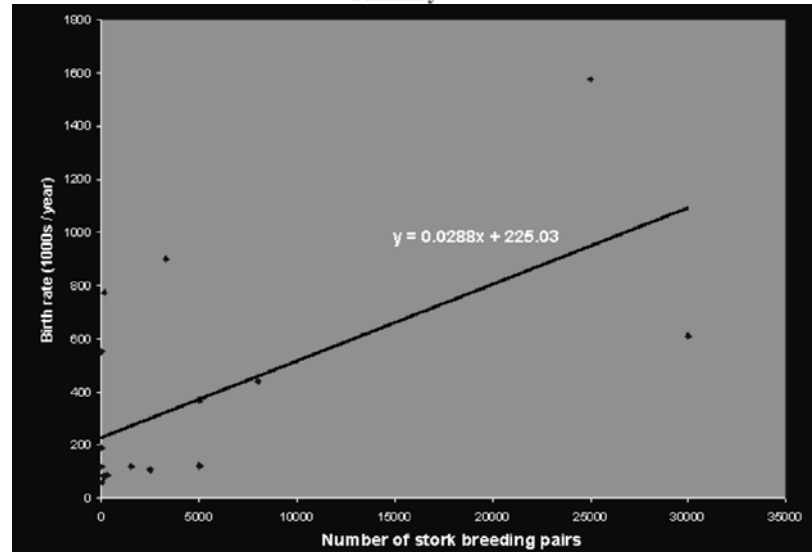
### KEYWORDS:

Teaching;  
Correlation;  
Significance;  
 $p$ -values.

*Robert Matthews*

Aston University, Birmingham, England.  
e-mail: rajm@compuserve.com

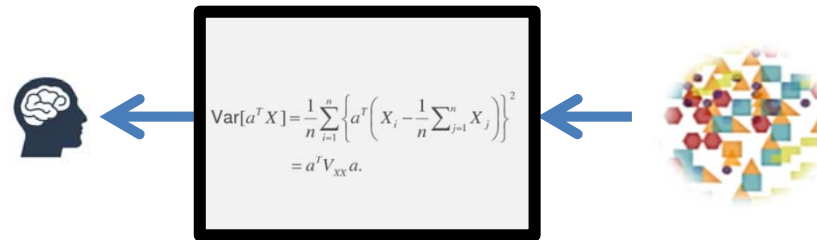
### Summary



Country	Area (km <sup>2</sup> )	Storks (pairs)	Humans (10 <sup>6</sup> )	Birth rate (10 <sup>3</sup> /yr)
Albania	28,750	100	3.2	83
Austria	83,860	300	7.6	87
Belgium	30,520	1	9.9	118
Bulgaria	111,000	5000	9.0	117
Denmark	43,100	9	5.1	59
France	544,000	140	56	774
Germany	357,000	3300	78	901
Greece	132,000	2500	10	106
Holland	41,900	4	15	188
Hungary	93,000	5000	11	124
Italy	301,280	5	57	551
Poland	312,680	30,000	38	610
Portugal	92,390	1500	10	120
Romania	237,500	5000	23	367
Spain	504,750	8000	39	439
Switzerland	41,290	150	6.7	82
Turkey	779,450	25,000	56	1576

**Table 1.** Geographic, human and stork data for 17 European countries

Robert Matthews 2000. Storks deliver babies ( $p = 0.008$ ). Teaching Statistics, 22, (2), 36-38.



$$\text{Var}[a^T X] = \frac{1}{n} \sum_{i=1}^n \left\{ a^T \left( X_i - \frac{1}{n} \sum_{j=1}^n X_j \right) \right\}^2$$

$$= a^T V_{XX} a.$$

Generalization error

Generalization  
plus human ex



iML = human inspection – bring in human conceptual knowledge

Andreas Holzinger et al. 2018. Interactive machine learning: experimental evidence for the human in the algorithmic loop. Springer/Nature Applied Intelligence, doi:10.1007/s10489-018-1361-5.

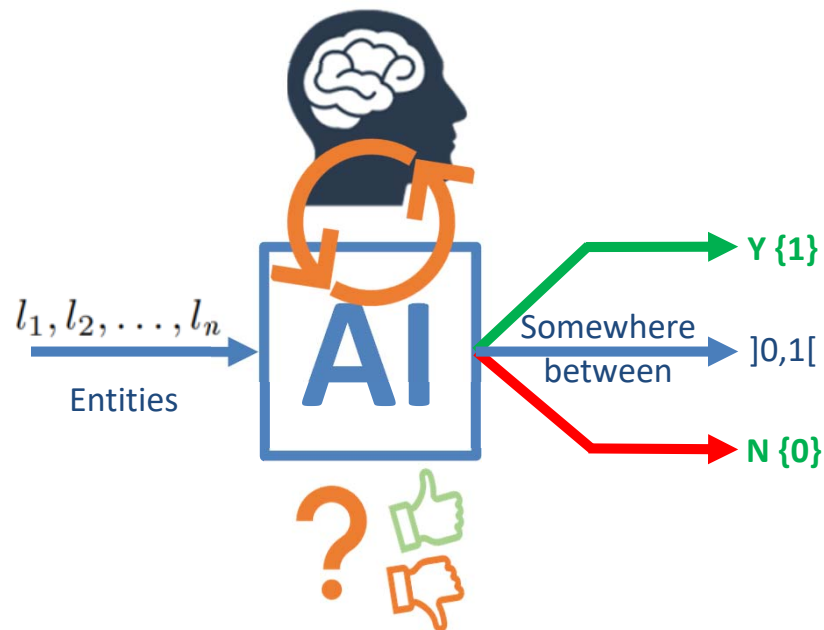
(Sometimes – **not** always!) humans are able ...

- to **understand** the context
- to make inferences **from little**, noisy, incomplete data sets
- to learn **relevant** representations
- to find shared **underlying explanatory** factors,
- with a **causal reasoning**

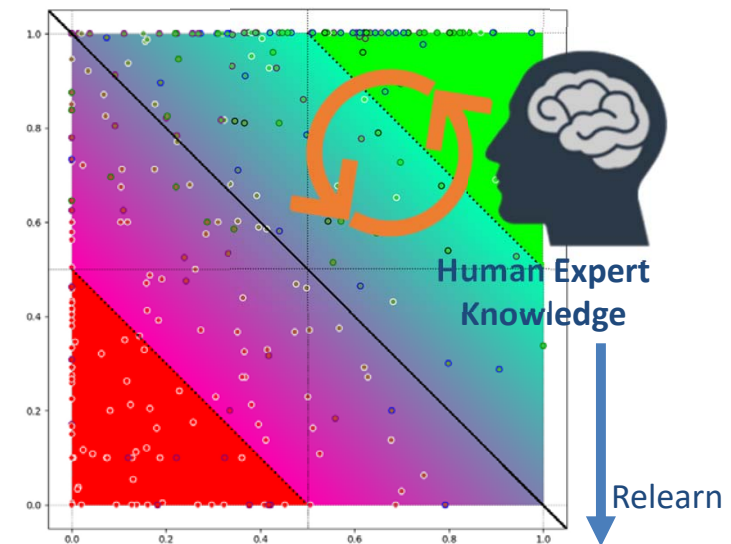
$P(Y|X) Y \rightarrow X$  (predict cause from effect) or  $P(Y|X) X \rightarrow Y$  (predict effect from cause)

Joshua B. Tenenbaum, Charles Kemp, Thomas L. Griffiths & Noah D. Goodman 2011. How to grow a mind: Statistics, structure, and abstraction. *Science*, 331, (6022), 1279-1285, doi:10.1126/science.1192788.

## The Problem



## Our Solution



**Y:**  $S_k(x, y) = (\min(1, x^k + y^k - 0.5^k))^{\frac{1}{k}}$

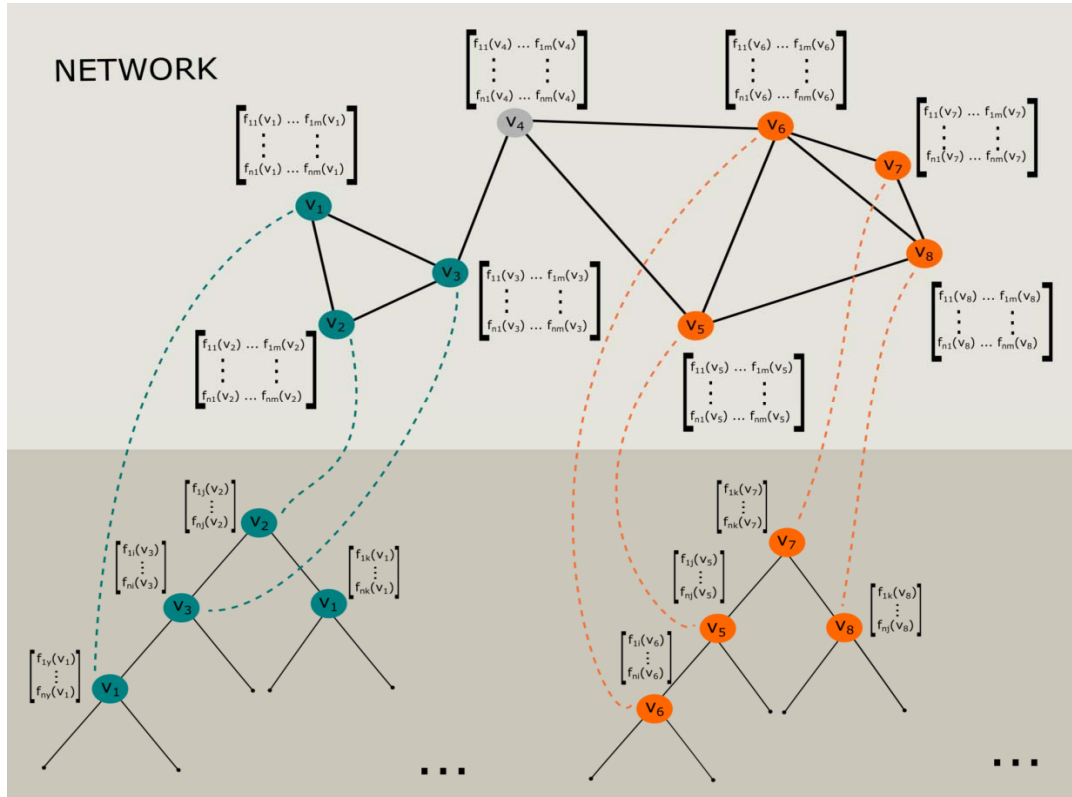
**N:**  $T_k(x, y) = (\max(1, x^k + y^k - 0.5^k))^{\frac{1}{k}}$

Miroslav Hudec, Erika Minarikova, Radko Mesiar, Anna Saranti & Andreas Holzinger (2021). Classification by ordinal sums of conjunctive and disjunctive functions for explainable AI and interpretable machine learning solutions. *Knowledge Based Systems*, 220, doi:10.1016/j.knosys.2021.106916.

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AAI-22 Interactive Machine Learning, February, 28, 2022

**Algorithm 1:** Greedy Decision Forest

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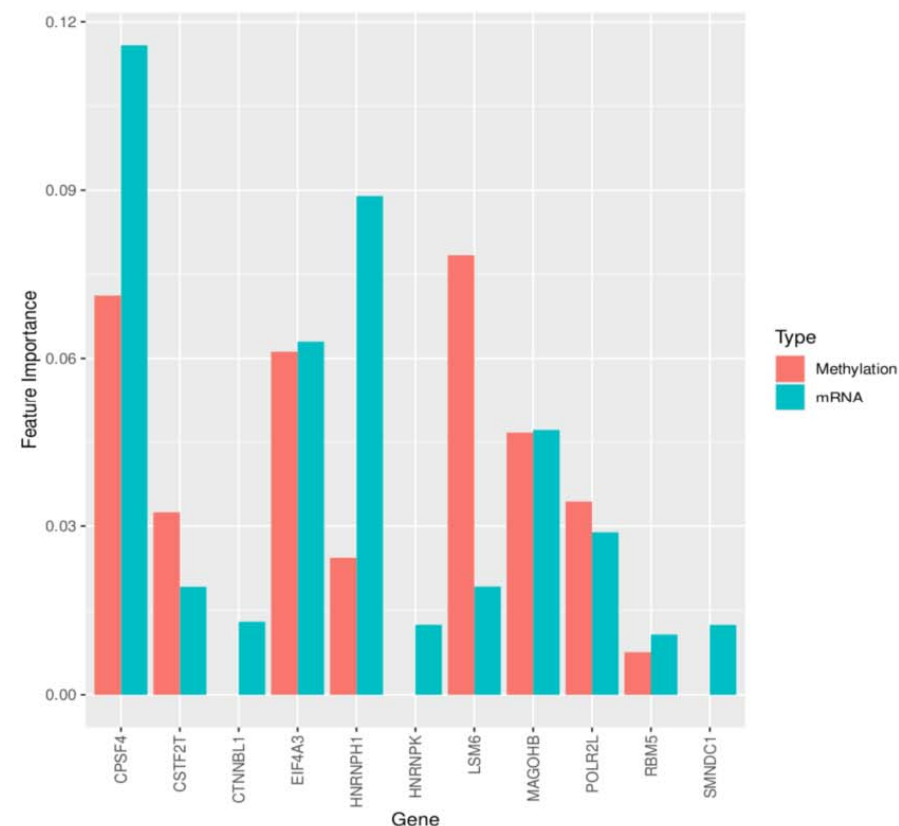
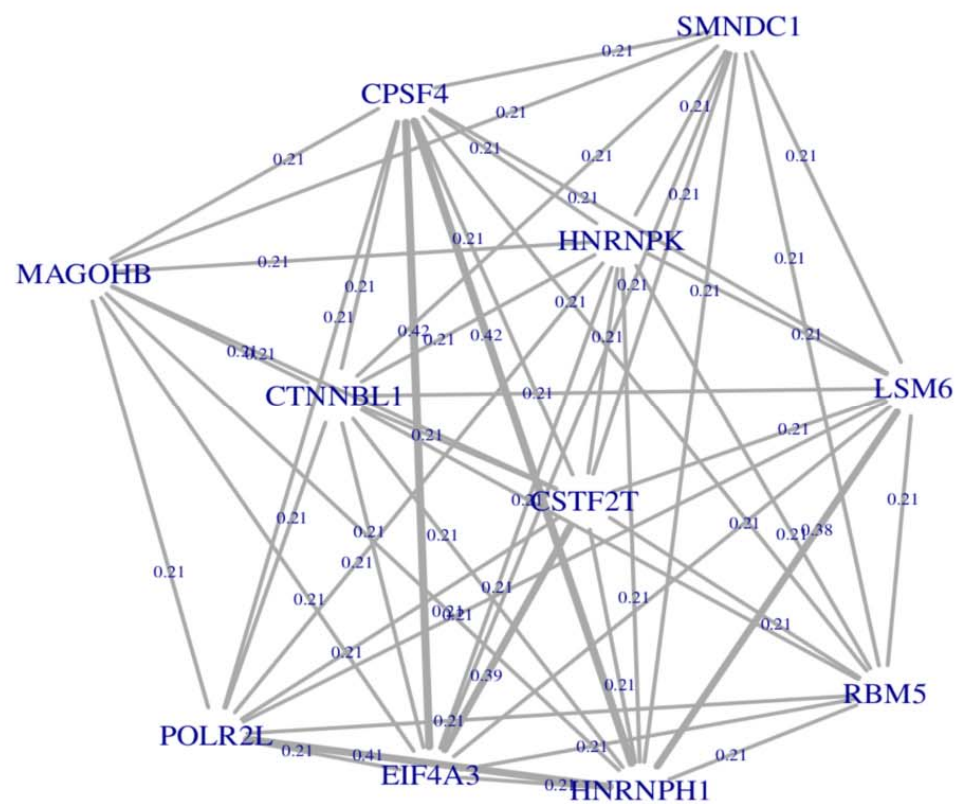
```

1 Given a Decision Forest:  $\{T_k(x, \Theta_k, X_k^G)\}$ ;
2 Given a graph:  $G = (V, E)$ ;
3  $k = \{1, \dots, ntree\}, t = 1$ ;
4  $mtry_k = \sqrt{\#V}$ ;
5  $X_k^G[t = 1] = X_k^G$ ;
6 while  $t \leq niter$  do
7   for  $k \leftarrow 1$  to  $ntree$  do
8      $Perf(T_k[t]) = \text{Performance of } T_k(x; \Theta_k, X_k^G)$ ;
9     if  $Perf(T_k[t]) \leq Perf(T_k[t - 1])$  then
10        $T_k[t] = T_k[t - 1]$ ;
11        $X_k^G[t] = X_k^G[t - 1]$ ;
12     else
13        $mtry_k[t] \leftarrow -$ ;
14        $X_k^G[t] = \text{RandomWalk}(G|X_k, mtry_k[t])$ ;
15     end
16   end
17    $\text{Sample } ntree \text{ trees according to } Perf\{T_k[t]\}$ ;
18    $t++$ ;
19 end

```

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Bastian Pfeifer, Anna Saranti, Andreas Holzinger (2021). Network Module Detection from Multi-Modal Node Features with a Greedy Decision Forest for Actionable Explainable AI. arXiv:2108.11674.

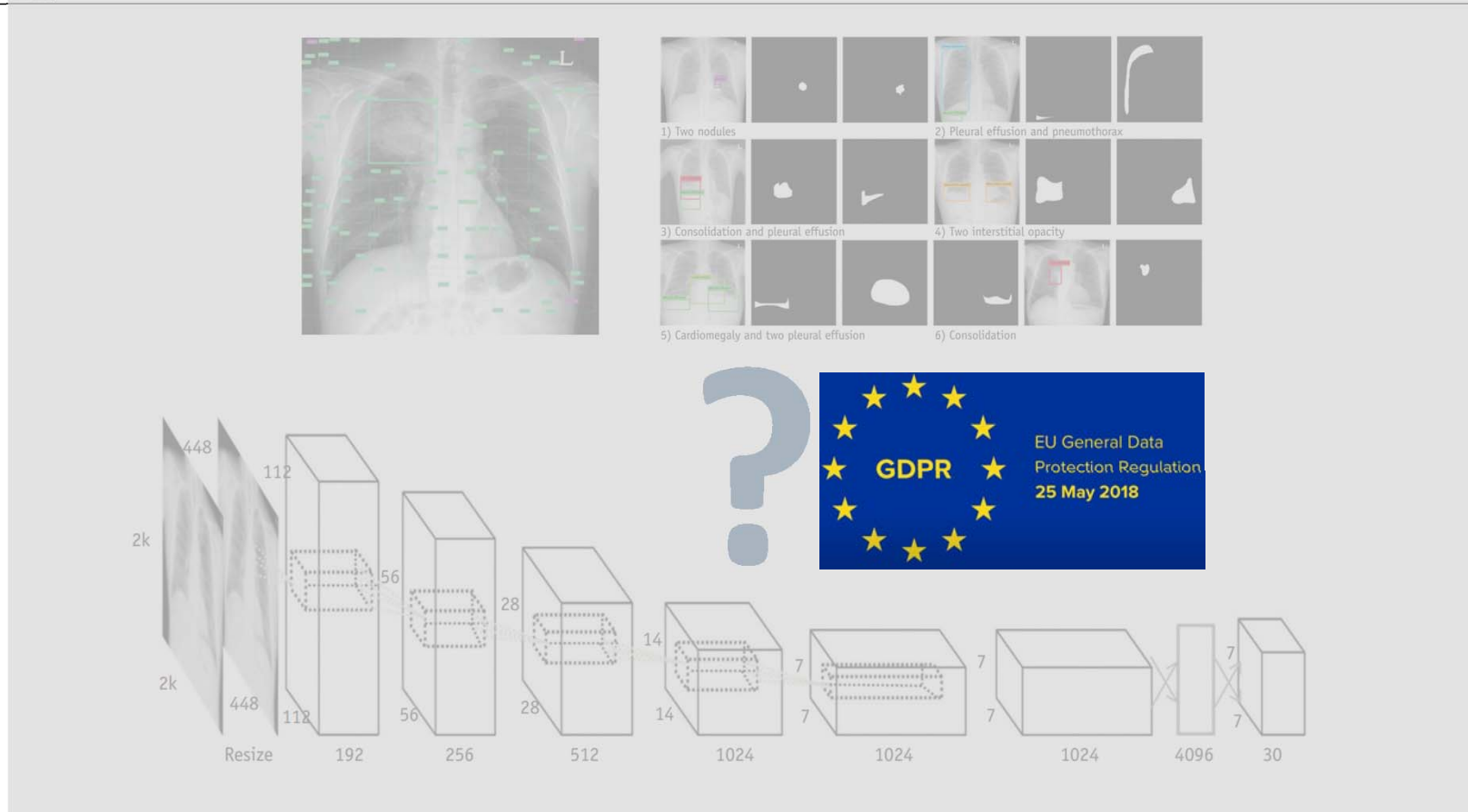


Bastian Pfeifer, Anna Saranti & Andreas Holzinger (2021). Network Module Detection from Multi-Modal Node Features with a Greedy Decision Forest for Actionable Explainable AI. arXiv:2108.11674.

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AAI-22 Interactive Machine Learning, February, 28, 2022

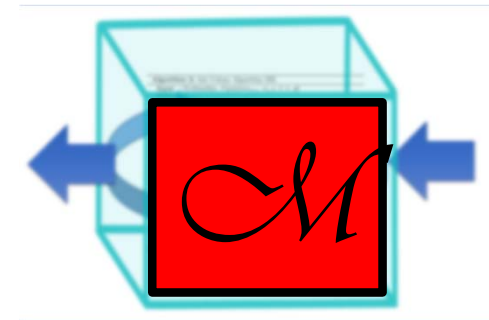
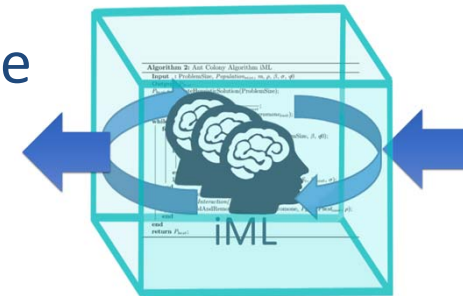


Karl Stoeger, David Schneeberger & Andreas Holzinger (2021).  
 Medical Artificial Intelligence: The European Legal Perspective.  
 Communications of the ACM, 64, (11), doi:10.1145/3458652.

June-Goo Lee, Sanghoon Jun, Young-Won Cho, Hyunna Lee, Guk Bae Kim, Joon Beom Seo & Namkug Kim 2017. Deep learning in medical imaging: general overview. Korean journal of radiology, 18, (4), 570-584, doi:10.3348/kjr.2017.18.4.570.

## (4) Methods of Explainability

- **Interpretable Models, = ante-hoc** - the “glass-box” model itself is *ante-hoc* interpretable, e.g. Regression, Naïve Bayes, Decision Trees, Graphs, ...
- **Interpreting Black-Box Models, = post-hoc** - the model is not interpretable and needs a post-hoc interpretability method  $\mathcal{M}$



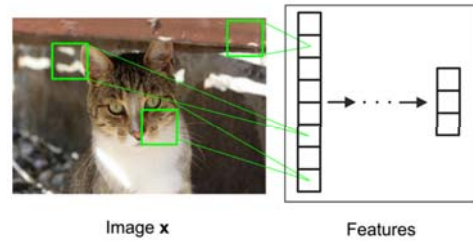
Andreas Holzinger, Chris Biemann, Constantinos S. Pattichis & Douglas B. Kell 2017. What do we need to build explainable AI systems for the medical domain? *arXiv:1712.09923*.

- 1) Gradients
- 2) Sensitivity Analysis
- 3) Simple Taylor expansions
- 4) Decomposition and Relevance Propagation  
(Pixel-RP, Layer-RP, Deep Taylor Decomposition, ...)
- 5) Excitation Backpropagation
- 6) Optimization (LIME, BETA, Smooth Grad, ...)  
BETA transparent approximation, ...)
- 7) Deconvolution (Occlusion-based, meaningful perturbations, ...)
- 8) Qualitative Testing with Concept Activation Vectors TCAV

Andreas Holzinger LV 706.315 From explainable AI to Causability, 3 ECTS course  
<https://human-centered.ai/explainable-ai-causability-2019> (course given since 2016)

$$f(x) \approx \sum_{d=1}^v R_d$$

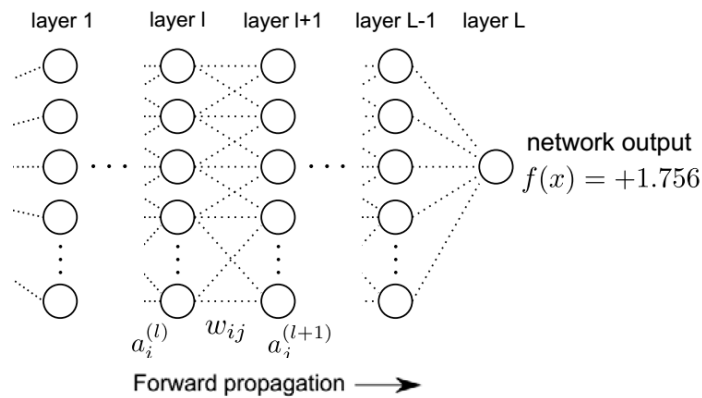
$$R_i = \left\| \frac{\partial}{\partial x_i} f(x) \right\|$$



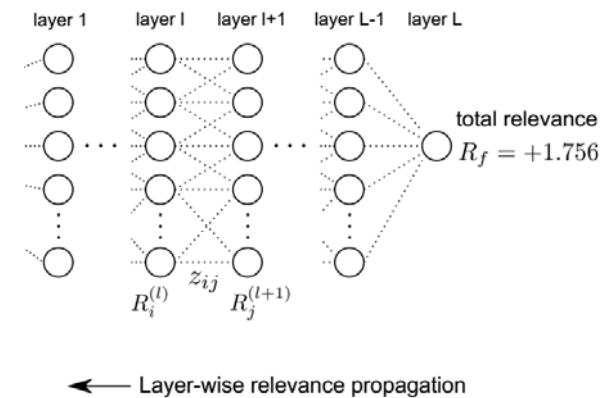
cat = ■  
 no cat = ■

Classifier output  $f(x)$

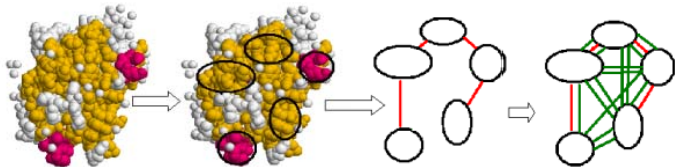
$$f(x) = \sum \text{Feature Relevances} = \sum \text{Pixel Relevances}$$



$$a_j^{(l+1)} = \sigma \left( \sum_i a_i^{(l)} w_{ij} + b_j^{(l+1)} \right)$$



$$R_i^{(l)} = \sum_j \frac{z_{ij}}{\sum_{i'} z_{i'j}} R_j^{(l+1)}$$



Karsten M Borgwardt, Cheng Soon Ong, Stefan Schöner, Svn Vishwanathan, Alex J Smola & Hans-Peter Kriegel (2005). Protein function prediction via graph kernels. *Bioinformatics*, 21, (suppl 1), i47-i56.

$G$  ... input graph

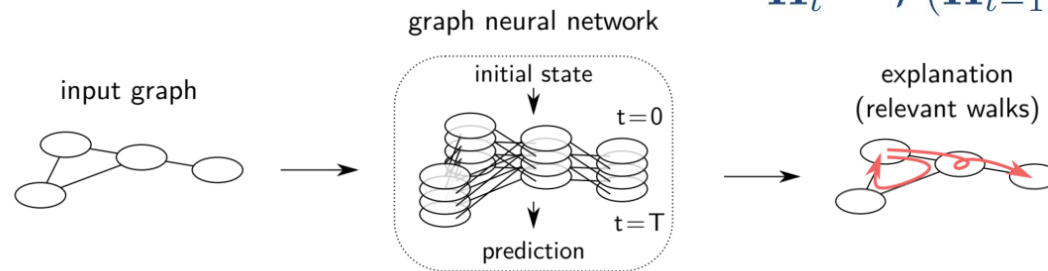
$$G = (\mathcal{V}, \mathcal{E})$$

$$\mathcal{V} = \{v_1, \dots, v_n\}$$

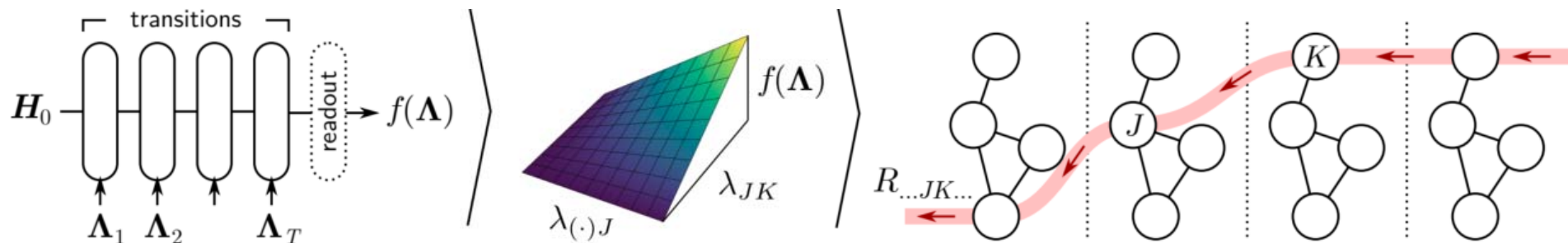
$$\mathcal{E} \subseteq \{(v_i, v_j) | v_i, v_j \in \mathcal{V}\}$$

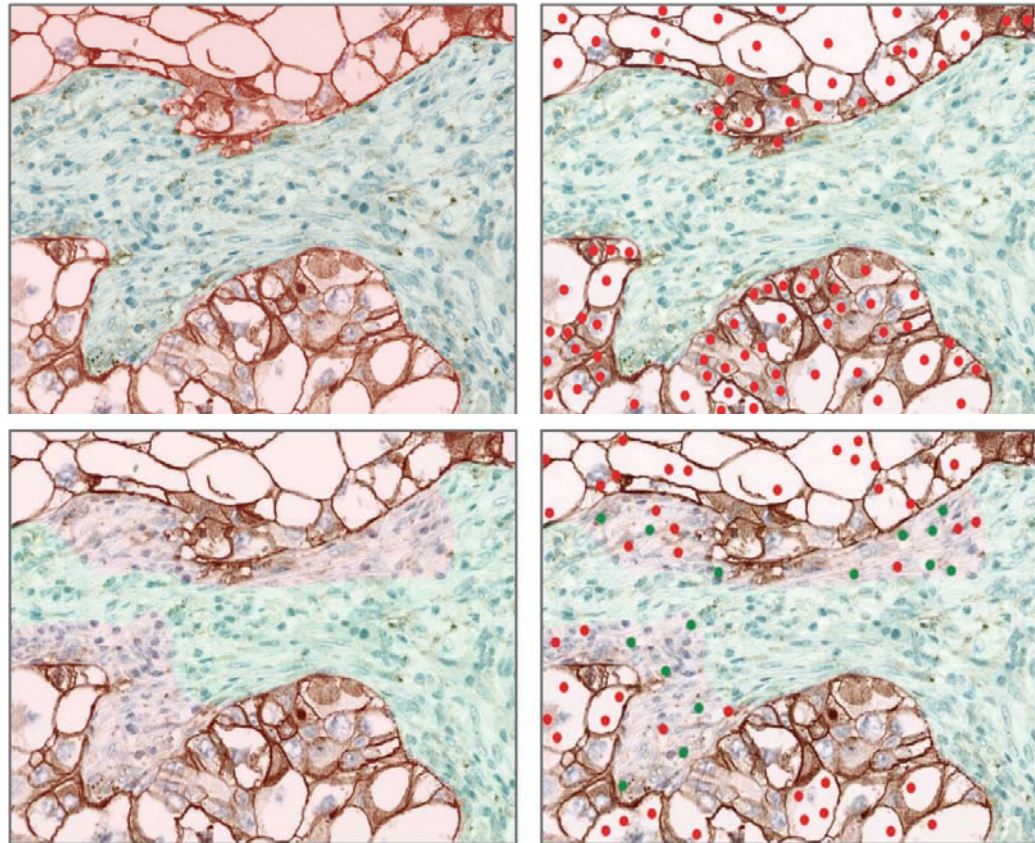
$H_0$  ... initial state

$$H_t = \mathcal{T}(H_{t-1}, \Lambda_t, W_t)$$



Thomas Schnake, Oliver Eberle, Jonas Lederer, Shinichi Nakajima, Kristof T. Schütt, Klaus-Robert Müller & Grégoire Montavon (2020). XAI for Graphs: Explaining Graph Neural Network Predictions by Identifying Relevant Walks. *arXiv:2006.03589*.



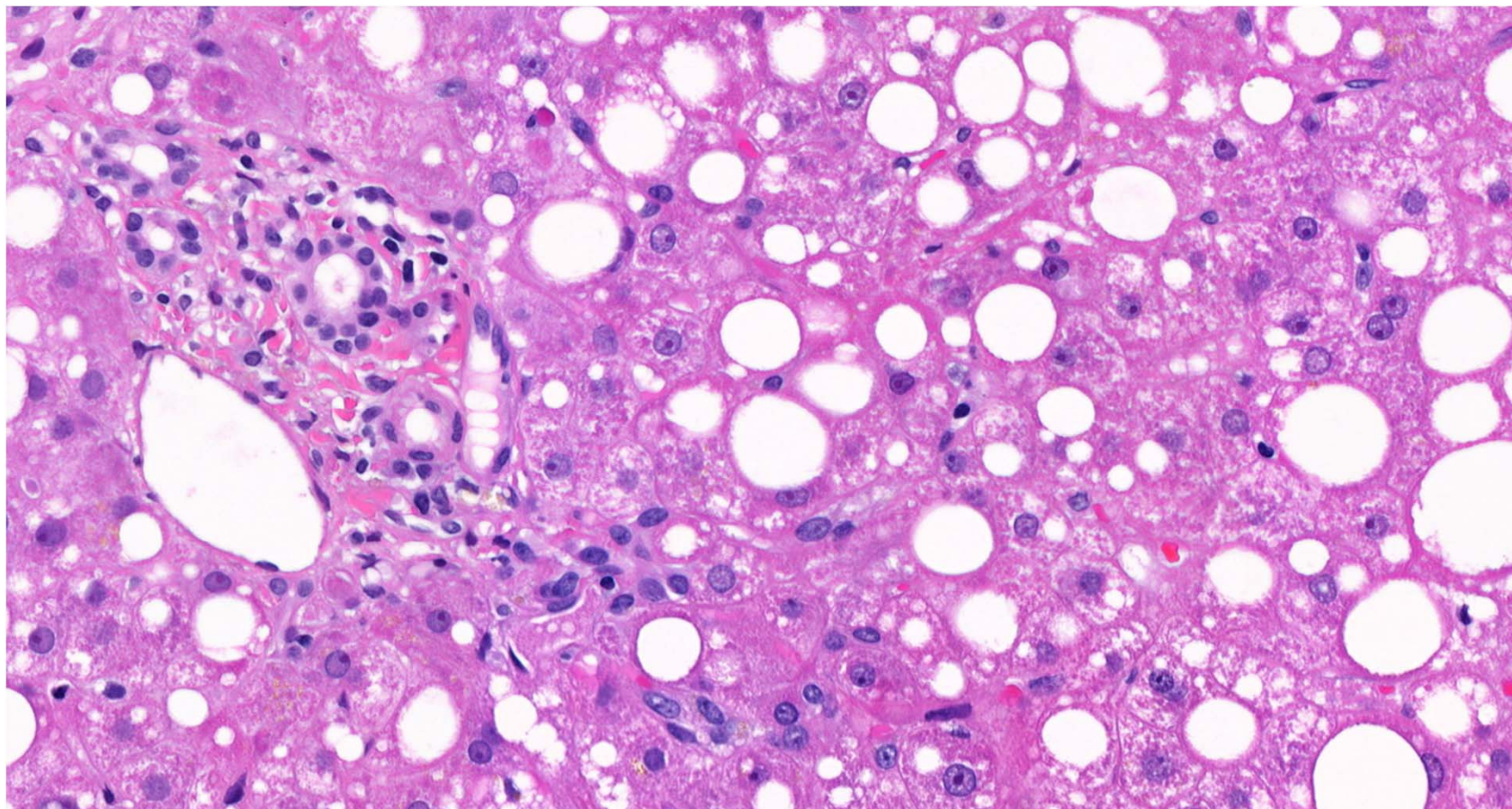


Andreas Holzinger & Heimo Mueller (2021). Toward Human-AI Interfaces to Support Explainability and Causability in Medical AI. *IEEE COMPUTER*, 54, (10), doi:10.1109/MC.2021.3092610.

**(5) Causability measures the quality of explanations obtained from (4)**

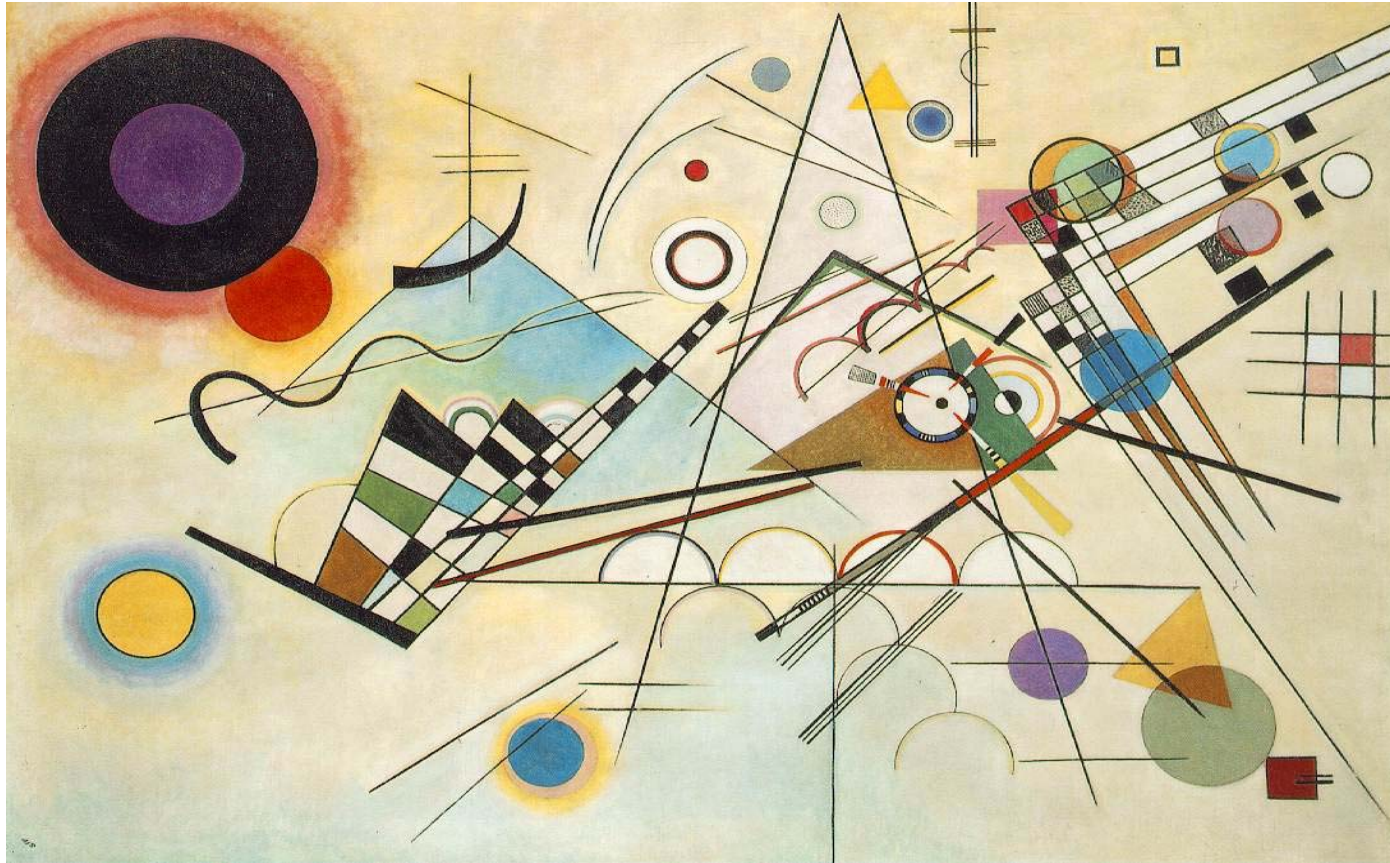
# Explainability is the first step

Andreas Holzinger, Chris Biemann, Constantinos S. Pattichis & Douglas B. Kell 2017. What do we need to build explainable AI systems for the medical domain? *arXiv:1712.09923*.



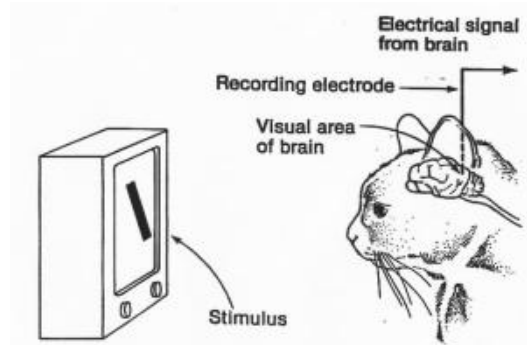
- := information provided by direct observation (empirical evidence) in contrast to information provided by inference
  - *Empirical evidence* = information acquired by observation or by experimentation in order to verify the truth (fit to reality) or falsify (non-fit to reality).
  - *Empirical inference* = drawing conclusions from empirical data (observations, measurements)
  - *Causal inference* = drawing conclusions about a causal connection based on the conditions of the occurrence of an effect
  - *Causal machine learning* is key to ethical AI in health to model explainability for bias avoidance and algorithmic fairness for decision making

Mattia Proserpi, Yi Guo, Matt Sperrin, James S. Koopman, Jae S. Min, Xing He, Shannan Rich, Mo Wang, Iain E. Buchan, Jiang Bian (2020). Causal inference and counterfactual prediction in machine learning for actionable healthcare. Nature Mach.Intelligence, 2, (7), 369-375, doi:10.1038/s42256-020-0197-y

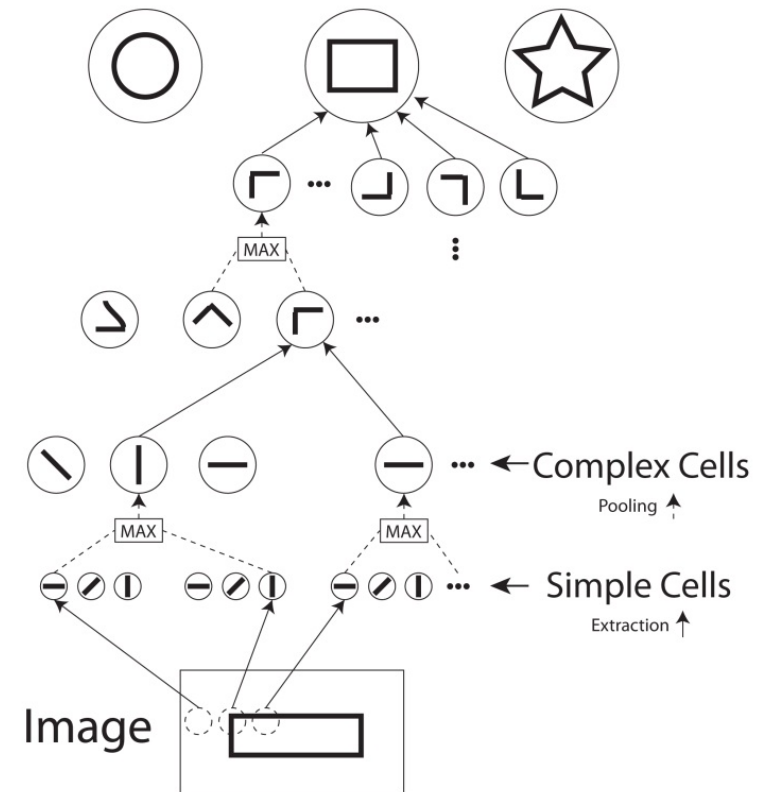
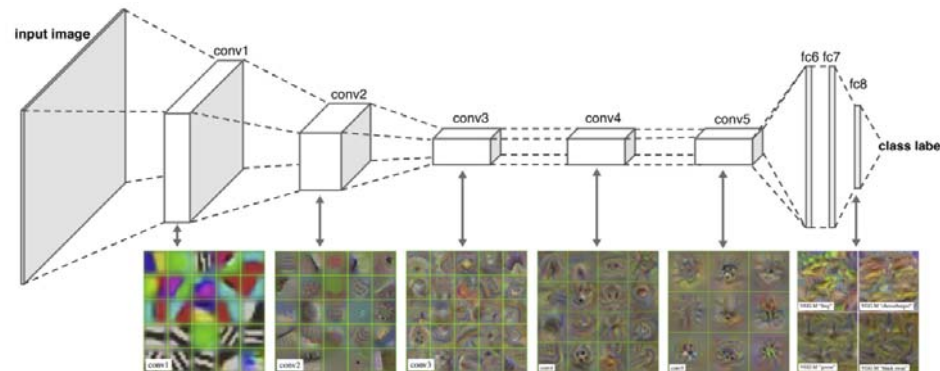


**Wassily Kandinsky**  
(1866 – 1944)

Komposition VIII, 1923, Solomon R. Guggenheim Museum, New York. Source: [https://de.wikipedia.org/wiki/Wassily\\_Kandinsky](https://de.wikipedia.org/wiki/Wassily_Kandinsky)  
Note: Image is in the public domain and is used according to UrhG §42 lit. f Abs 1 as "Belegfunktion" for discussion with students

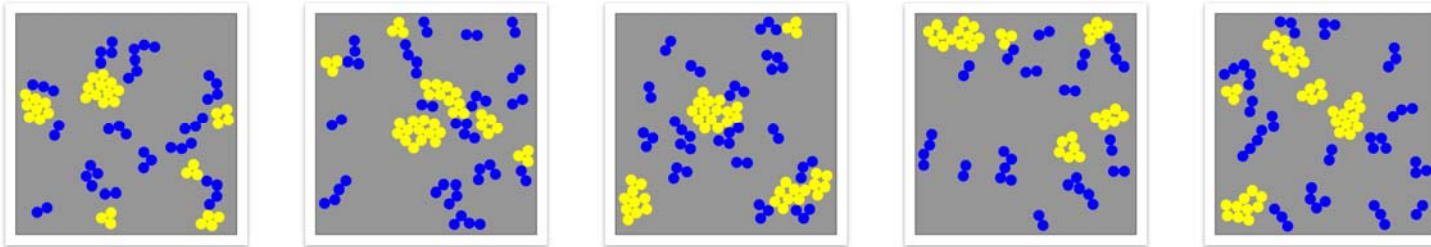


David H. Hubel & Torsten N. Wiesel 1962. Receptive fields, binocular interaction and functional architecture in the cat's visual cortex. The Journal of Physiology, 160, (1), 106-154, doi:10.1113/jphysiol.1962.sp006837

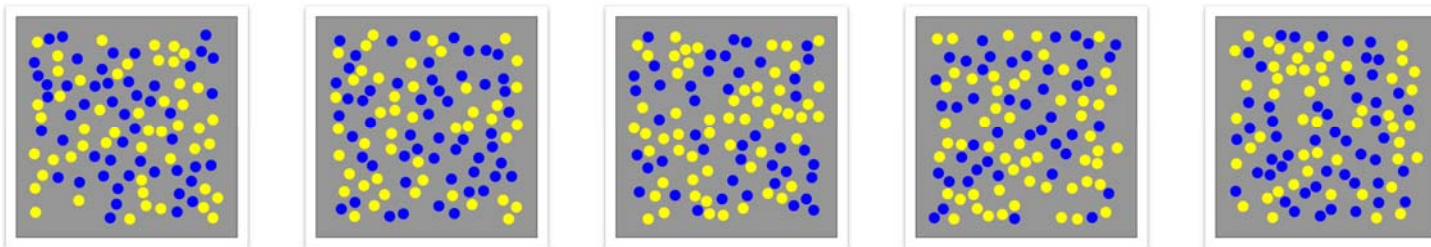


Source: <https://www.intechopen.com/books/visual-cortex-current-status-and-perspectives/models-of-information-processing-in-the-visual-cortex>

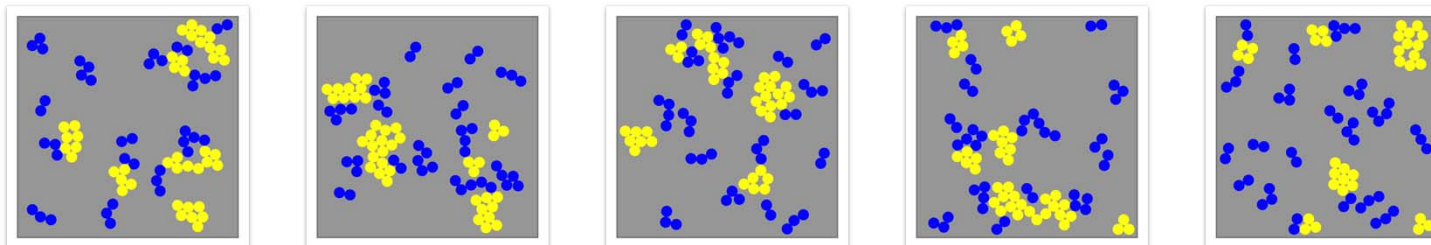
A) True (the cells are smaller and closer together – it is an tumor ...)



B) False



C) Counterfactual (What if the cells are slightly bigger ?)



[GO BACK TO LIST OF PATTERNS](#)
[GO TO NEXT PATTERN](#)

## What is Pattern VIII?

Hypothesis 1

There are 4 objects



Hypothesis 2

There is always a triangle



Hypothesis 3

There is more than 1 color



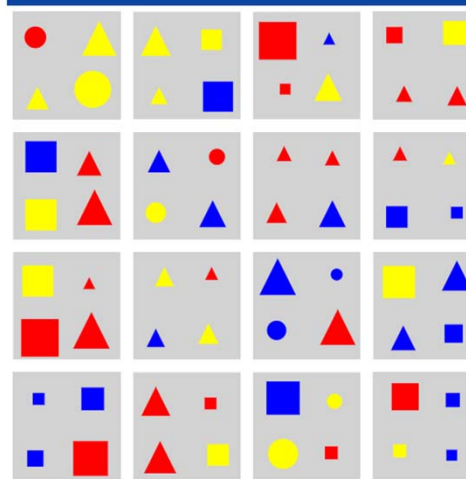
+ NEW HYPOTHESIS

! HINT

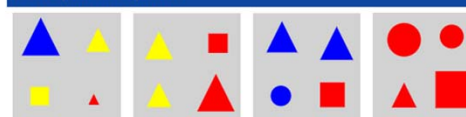
? SOLUTION

Previous **1** 2 3 Next

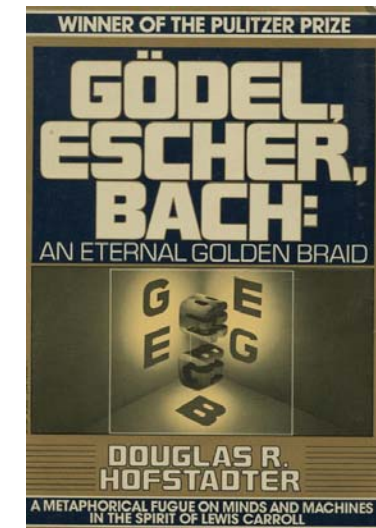
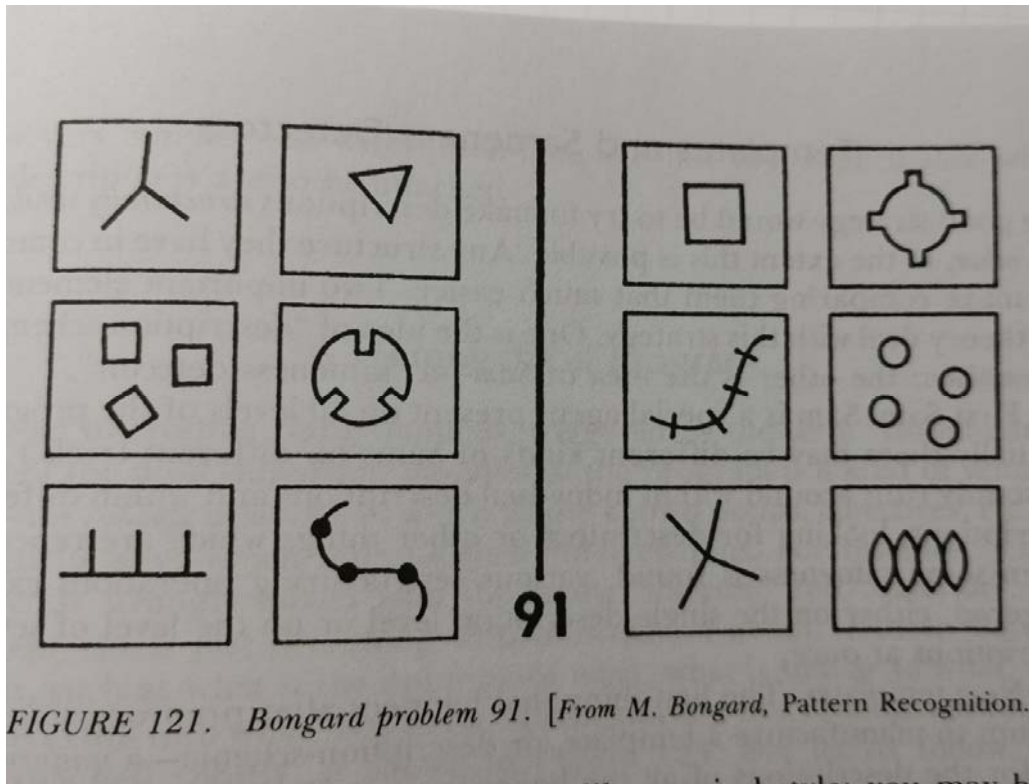
Part of the pattern



Not part of the pattern

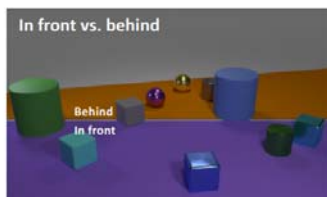
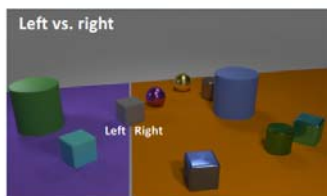


Andreas Holzinger, Michael Kickmeier-Rust & Heimo Mueller 2019. KANDINSKY Patterns as IQ-Test for machine learning. Springer Lecture Notes LNCS 11713. Cham (CH): Springer Nature Switzerland, pp. 1-14, doi:10.1007/978-3-030-29726-8\_1.

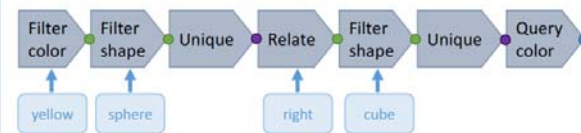


Douglas R. Hofstadter (1979)  
Gödel, Escher, Bach:  
An Eternal Golden Braid,  
New York: Basic Books.

Bongard, M. Mikhail, 1967. The problem of recognition (in Russian), Moscow, Nauka (1970 in English)

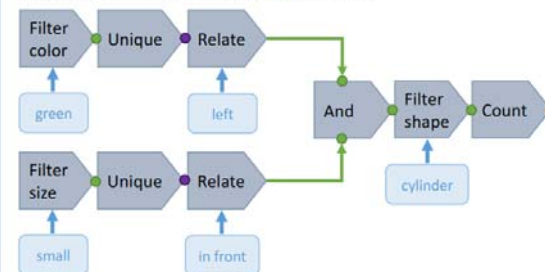


Sample chain-structured question:



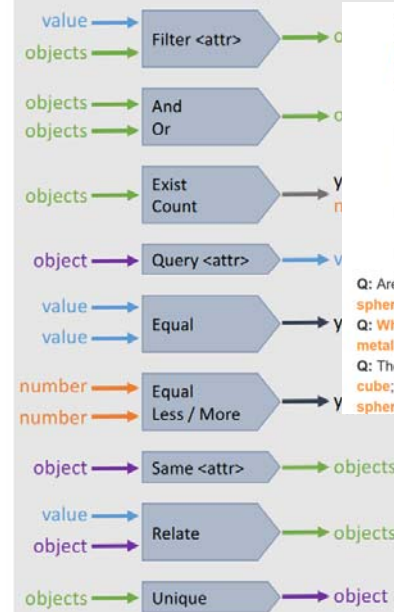
What color is the cube to the right of the yellow sphere?

Sample tree-structured question:



How many cylinders are in front of the small thing and on the left side of the green object?

CLEVR function catalog



Questions in CLEVR test various aspects of visual reasoning including **attribute identification, counting, comparison, spatial relationships, and logical operations.**



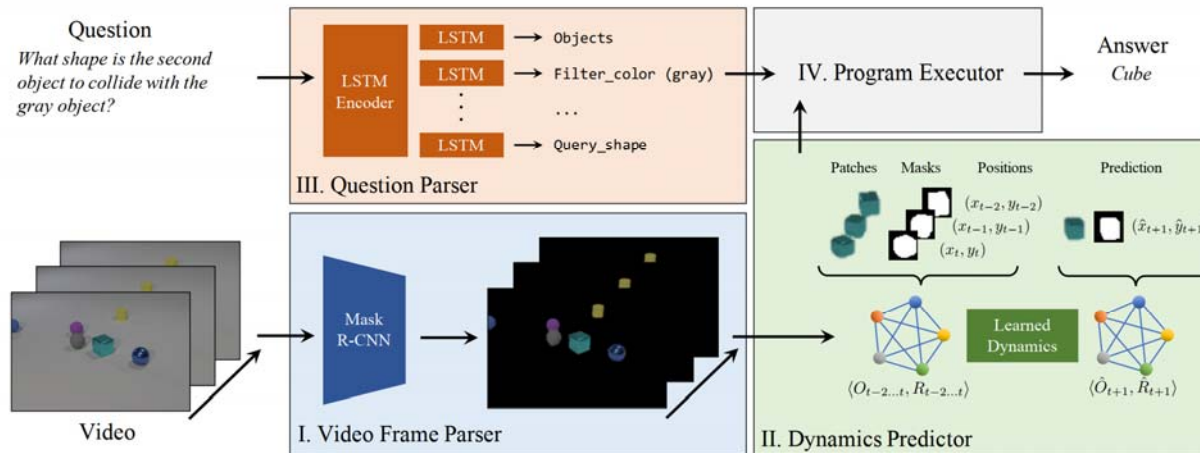
Q: Are there an **equal number** of **large things** and **metal spheres**?

Q: What **size** is the **cylinder** that is **left** of the **brown metal thing** that is **left** of the **big sphere**?

Q: There is a **sphere** with the **same size** as the **metal cube**; is it **made of the same material** as the **small red sphere**?

<https://cs.stanford.edu/people/jcjohns/clevr/>

Justin Johnson, Bharath Hariharan, Laurens Van Der Maaten, Li Fei-Fei, C. Lawrence Zitnick & Ross Girshick.  
 CLEVR: A diagnostic dataset for compositional language and elementary visual reasoning. Proceedings of the  
 IEEE Conference on Computer Vision and Pattern Recognition (CVPR), 2017 Hawaii. IEEE.

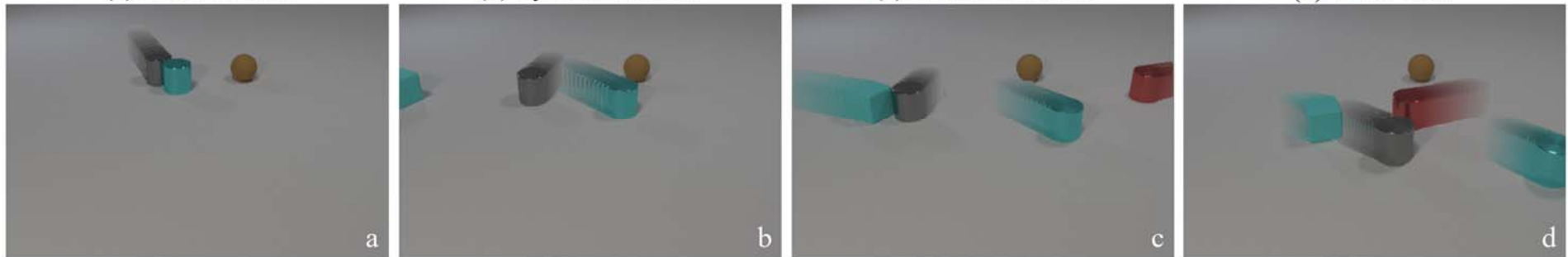


(a) First collision

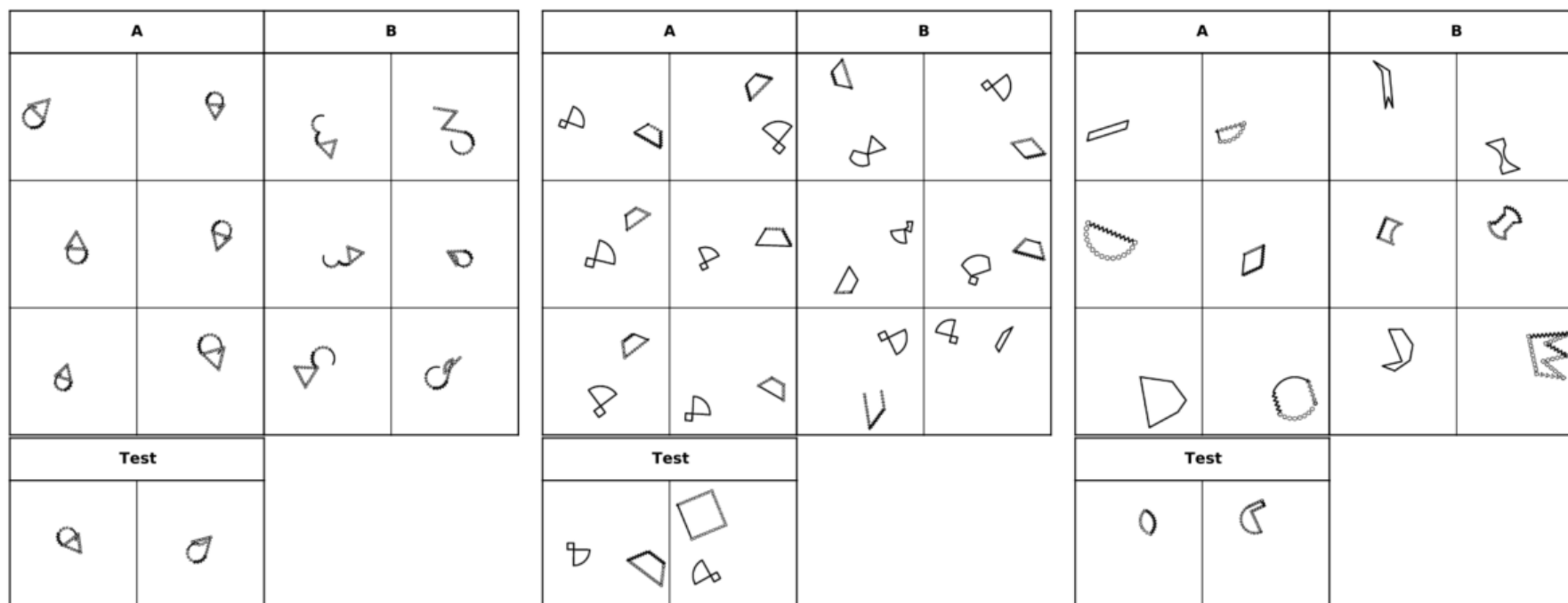
(b) Cyan cube enters

(c) Second collision

(d) Video ends



Kexin Yi, Chuang Gan, Yunzhu Li, Pushmeet Kohli, Jiajun Wu, Antonio Torralba & Joshua B. Tenenbaum (2019). CLEVRER: Collision events for video representation and reasoning. arXiv:1910.01442.



(a) free-from shape problem

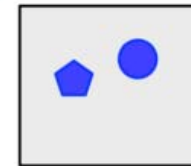
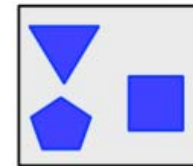
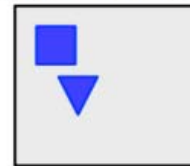
(b) basic shape problem

(c) abstract shape problem

Weili Nie, Zhiding Yu, Lei Mao, Ankit B Patel, Yuke Zhu & Anima Anandkumar (2020). BONGARD-LOGO: A New Benchmark for Human-Level Concept Learning and Reasoning. Advances in Neural Information Processing Systems, 33.

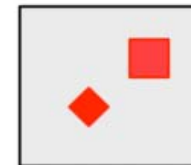
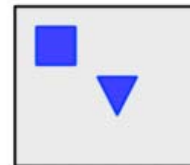
for-all  $x \in S$  ( $\text{color?}(x) = \text{"blue"}$ ) and ( $\text{all}(\text{size?}(S) = \text{size?}(x))$ )

All objects are blue and have the same size



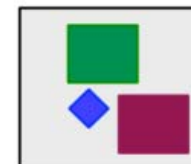
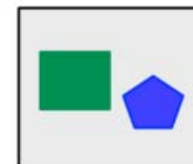
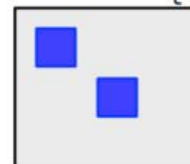
for-all  $x \in S$  ( $\text{all}(\text{color?}(x) = \text{color?}(S))$ )

All objects in the scene have the same color



exists  $x \in S$  ( $\text{color?}(x) = \text{"blue"}$ ) and  $\text{all}(\text{shape?}(S_{\{-x\}}) = \text{"square"})$

There exists a blue object in the scene and the rest of the objects are squares



$\mathcal{G}$ : Context Free Grammar

**Variables**

$x \triangleq$  Object in scene

$S \triangleq$  All objects

$S_{\{-x\}} \triangleq S/\{x\}$

**Quantifiers**

for-all

exists

**Functions**

color? location?

shape? size?

material? all

**Operators**

and Greater(>)

or Lesser(<)

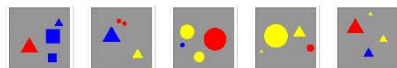
not =

Ramakrishna Vedantam, Arthur Szlam, Maximilian Nickel, Ari Morcos & Brenden Lake (2020).

CURI: A Benchmark for Productive Concept Learning Under Uncertainty. arXiv:2010.02855.

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#KANDINSKYPatterns our Swiss-Knife for the study of explainable-AI

**ABSTRACT**

*KANDINSKY*Patterns (yes, named after the famous artist Wassily Kandinsky) are mathematically describable, simple, self-contained, hence controllable test data sets for the development, validation and training of explainability in artificial intelligence (AI) and machine learning (ML). Whilst our KANDINSKY Patterns have these computationally manageable properties, they are at the same time easily distinguishable from human observers. Consequently, controlled patterns can be described by both humans and algorithms.

We define a KANDINSKY Pattern as a set of KANDINSKY Figures, where for each figure an "infallible authority" (ground truth) defines that this figure belongs to the KANDINSKY Pattern. With this simple principle we build training and validation data sets for automatic interpretability and context learning.

**KANDINSKYPATTERNS AT TEDX****KANDINSKY ARTIFICIAL INTELLIGENCE EXPLANATION CHALLENGE**

Here we challenge the international machine learning community to generate machine explanations

**KANDINSKY HUMAN INTELLIGENCE EXPLANATION CHALLENGE**

Here we challenge any human individual to take part in this experiment and to generate human explanations

**HCAI GITHUB REPOSITORY****OPEN STUDENTS THESES**

Human-AI Interface DESIGNER  
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**LATEST NEWS**

August 25-28, 2020, Machine Learning & Knowledge Extraction, LNCS 12279 published !  
 2020-08-21 · 12:15

Our Springer LNCS 12279 Machine Learning & Knowledge Extraction just been published.

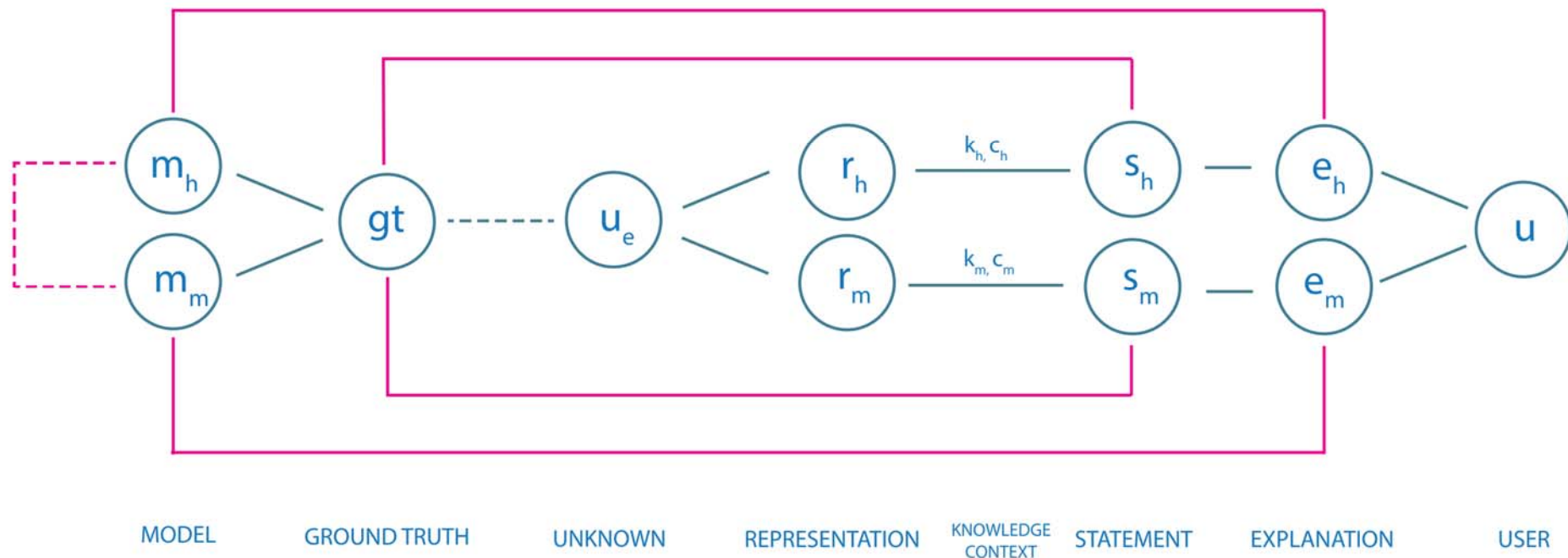
<https://arxiv.org/abs/2103.00519>

# Measuring the quality of Explanations: The Systems Causability Scale

Andreas Holzinger, Andre Carrington & Heimo Müller 2020. Measuring the Quality of Explanations: The System Causability Scale (SCS). Comparing Human and Machine Explanations. KI - Künstliche Intelligenz (German Journal of Artificial intelligence), Special Issue on Interactive Machine Learning, Edited by Kristian Kersting, TU Darmstadt, 34, (2), doi:10.1007/s13218-020-00636-z

- Causability is neither a typo nor a synonym for Causality
- Causa-bil-ity ... in reference to ... Usa-bil-ity.
- While xAI is about implementing transparency and traceability, Causability is about the measurement of the quality of explanations.
- **Explainability** := technically highlights decision relevant parts of machine representations and machine models i.e., parts which contributed to model accuracy in training, or to a specific prediction.
  - Explainability does not refer to a human model!
- **Causability** := the measurable extent to which an explanation of a statement to a user achieves a specified level of causal understanding with effectiveness, efficiency, satisfaction in a specified context of use.
  - Causability does refer to a human model!

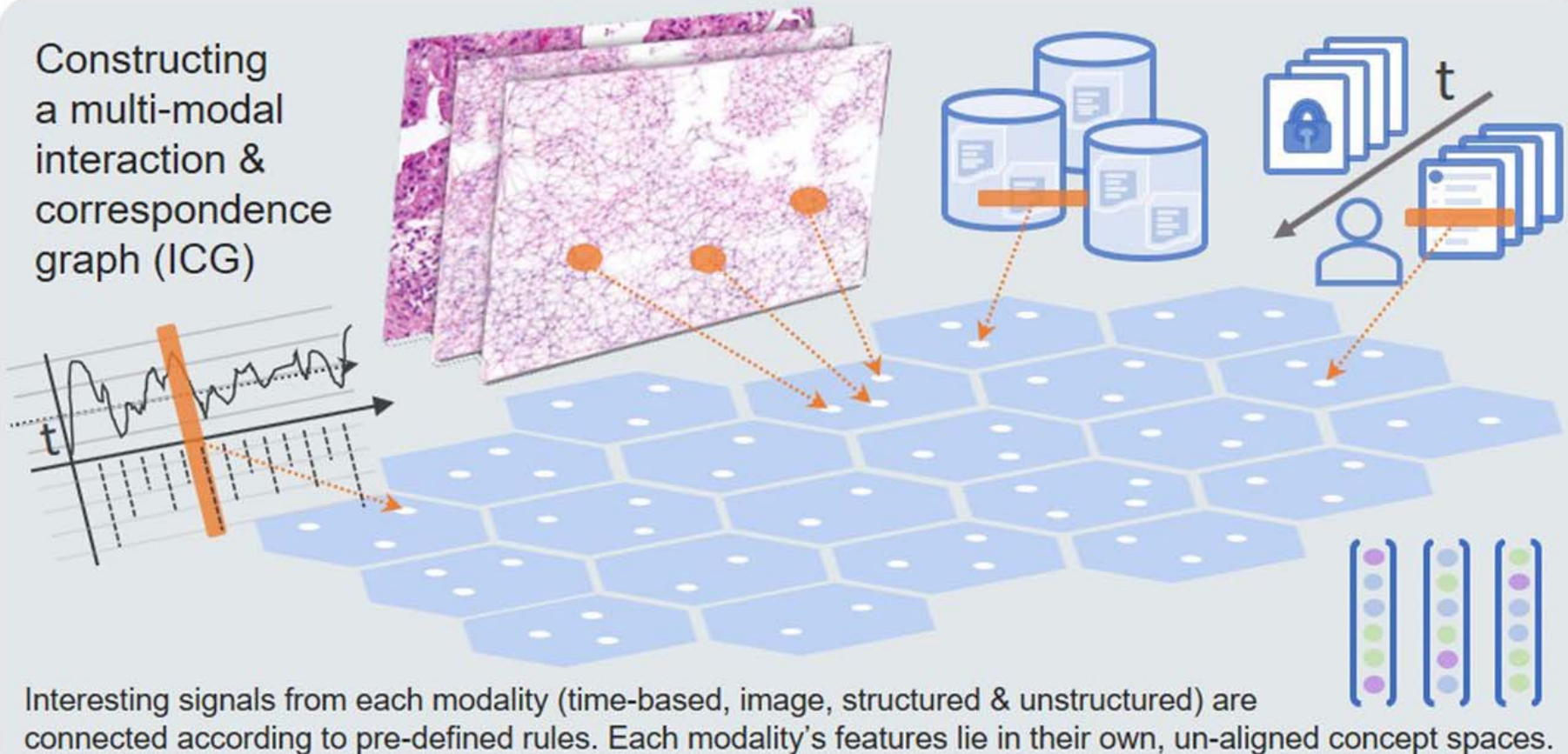
Andreas Holzinger, Georg Langs, Helmut Denk, Kurt Zatloukal & Heimo Mueller 2019. Causability and Explainability of Artificial Intelligence in Medicine. Wiley Interdisciplinary Reviews: Data Mining and Knowledge Discovery, 9, (4), doi:10.1002/widm.1312.



Andreas Holzinger, Andre Carrington & Heimo Müller 2020. Measuring the Quality of Explanations: The System Causability Scale (SCS). Comparing Human and Machine Explanations. KI - Künstliche Intelligenz (German Journal of Artificial intelligence), Special Issue on Interactive Machine Learning, Edited by Kristian Kersting, TU Darmstadt, 34, (2), doi:10.1007/s13218-020-00636-z.

# Conclusio

Constructing  
a multi-modal  
interaction &  
correspondence  
graph (ICG)

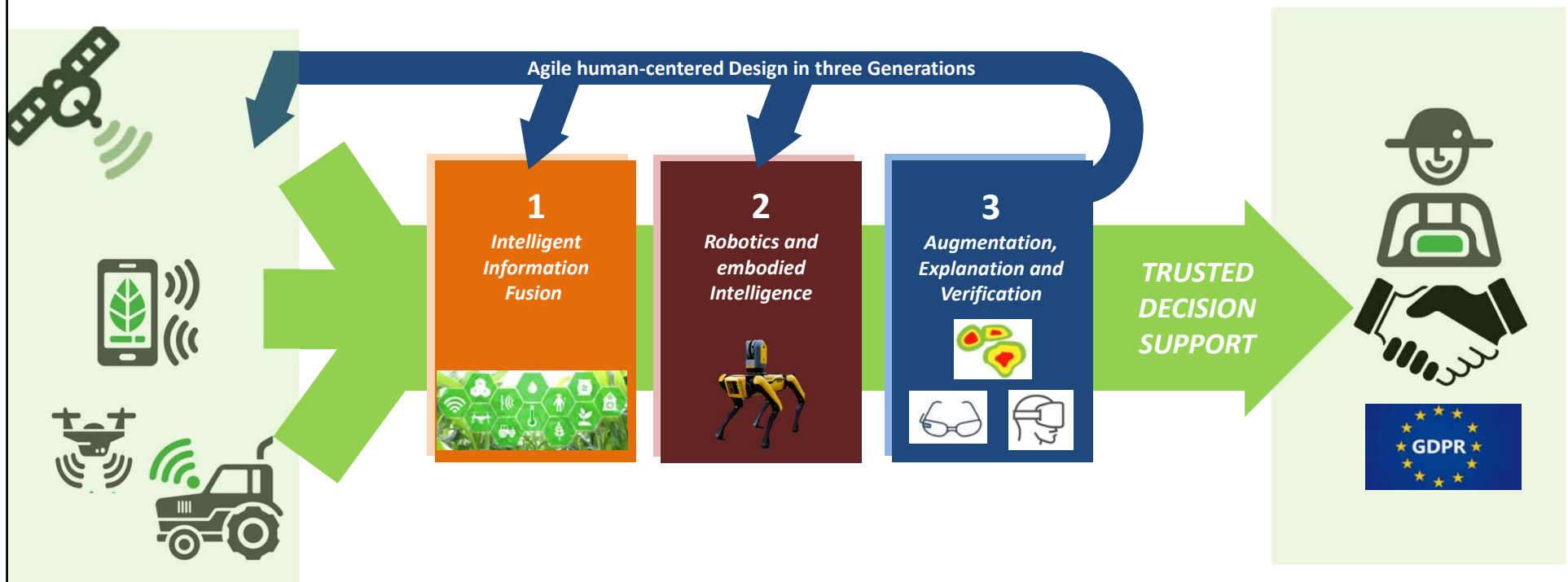


Andreas Holzinger, Bernd Malle, Anna Saranti & Bastian Pfeifer (2021). Towards Multi-Modal Causability with Graph Neural Networks enabling Information Fusion for explainable AI. Information Fusion, 71, (7), 28-37, doi:10.1016/j.inffus.2021.01.008.

[andreas.holzinger AT human-centered.ai](mailto:andreas.holzinger AT human-centered.ai)

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AAI-22 Interactive Machine Learning, February, 28, 2022



Andreas Holzinger, Anna Saranti, Alessa Angerschmid, Carl Orge Retzlaff, Andreas Gronauer, Viktoria Motsch, Christoph Gollob, Karl Stampfer (2022). Digital Transformation in Smart Farm and Forest Operations needs Human-Centered AI: Challenges and Future Directions. Sensors (in print)



**Human-Centered AI aligns AI with human values, ethical principles and legal requirements.**

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- Andreas Holzinger, Edgar Weippl, A Min Tjoa & Peter Kieseberg (2021). Digital Transformation for Sustainable Development Goals (SDGs) - a Security, Safety and Privacy Perspective on AI. *Springer Lecture Notes in Computer Science*, LNCS 12844. Cham: Springer, pp. 1-20, doi:10.1007/978-3-030-84060-0\_1
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- Shane O'sullivan, Simon Leonard, Andreas Holzinger, Colin Allen, Fiorella Battaglia, Nathalie Nevejans, Fijs W.B. Van Leeuwen, Mohammed Imran Sajid, Michael Friebe, Hutan Ashrafian, Helmut Heinsen, Dominic Wichmann & Margaret Hartnett (2020). Anatomy 101 for AI-driven robotics: Explanatory, ethical and legal frameworks for development of cadaveric skills training standards in autonomous robotic surgery/autopsy. *The International Journal of Medical Robotics and Computer Assisted Surgery*, doi:10.1002/rcs.2020
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